

# DSLVD1047 3.3-V LVDS Quad Channel High-Speed Differential Line Driver

## 1 Features

- Designed for Signaling Rates up to 400-Mbps
- 3.3-V Power Supply Design
- 300-ps Typical Differential Skew
- 400-ps Maximum Differential Skew
- 1.7-ns Maximum Propagation Delay
- $\pm 350$ -mV Differential Signaling
- Low Power Dissipation (13 mW at 3.3-V Static)
- Interoperable With Existing 5-V LVDS Receivers
- High impedance on LVDS Outputs on Power Down
- Flow-Through Pinout Simplifies PCB Layout
- Meets or Exceeds TIA/EIA-644 LVDS Standard
- Industrial Operating Temperature Range ( $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ )
- Available in TSSOP Package

## 2 Applications

- Multifunction Printers
- Board-to-Board Communication
- Test and Measurement
- Printers
- Data Center Interconnect
- Lab Instrumentation
- Ultrasound Scanners

## 3 Description

The DSLVD1047 device is a quad CMOS flow-through differential line driver designed for applications requiring ultra-low power dissipation and high data rates. The device is designed to support data rates in excess of 400 Mbps (200 MHz) using Low Voltage Differential Signaling (LVDS) technology.

The DSLVD1047 accepts low voltage TTL/CMOS input levels and translates them to low voltage (350 mV) differential output signals. In addition, the driver supports a TRI-STATE function that may be used to disable the output stage, disabling the load current, and thus dropping the device to an ultra low idle power state of 13 mW typical. The DSLVD1047 has a flow-through pinout for easy PCB layout.

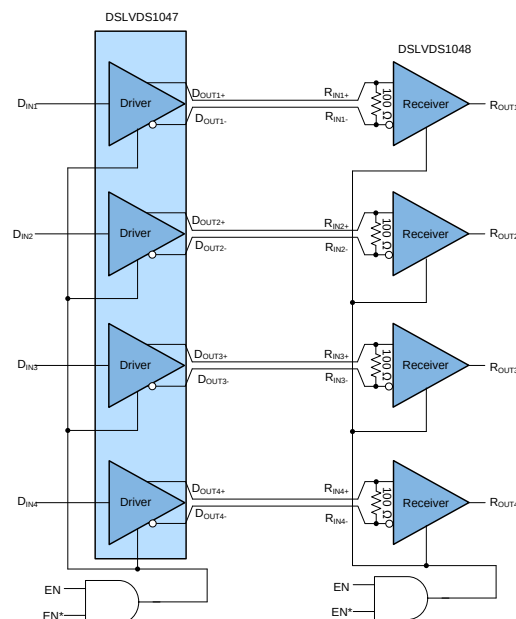
The EN and EN\* inputs are ANDed together and control the TRI-STATE outputs. The enables are common to all four drivers. The and companion line receiver (DSLVD1048) provide a new alternative to high power psuedo-ECL devices for high speed point-to-point interface applications.

### Device Information<sup>(1)</sup>

| PART NUMBER | PACKAGE    | BODY SIZE (NOM)          |
|-------------|------------|--------------------------|
| DSLVD1047   | TSSOP (16) | 5.00 mm $\times$ 4.40 mm |

(1) For all available packages, see the orderable addendum at the end of the data sheet.

**Figure 1. Application Diagram**



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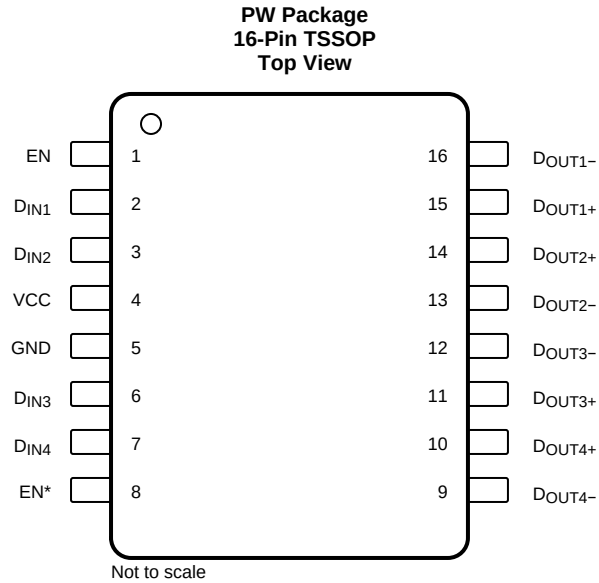
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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| DATE           | REVISION | NOTES            |
|----------------|----------|------------------|
| September 2018 | *        | Initial release. |

## 5 Pin Configuration and Functions



### Pin Functions

| PIN |                    | I/O | DESCRIPTION                                                                                                                                                                                   |
|-----|--------------------|-----|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| NO. | NAME               |     |                                                                                                                                                                                               |
| 2   | D <sub>IN1</sub>   | I   | Driver input pin, TTL/CMOS compatible                                                                                                                                                         |
| 3   | D <sub>IN2</sub>   |     |                                                                                                                                                                                               |
| 6   | D <sub>IN3</sub>   |     |                                                                                                                                                                                               |
| 7   | D <sub>IN4</sub>   |     |                                                                                                                                                                                               |
| 10  | D <sub>OUT4+</sub> | O   | Non-inverting driver output pin, LVDS levels                                                                                                                                                  |
| 11  | D <sub>OUT3+</sub> |     |                                                                                                                                                                                               |
| 14  | D <sub>OUT2+</sub> |     |                                                                                                                                                                                               |
| 15  | D <sub>OUT1+</sub> |     |                                                                                                                                                                                               |
| 9   | D <sub>OUT4-</sub> | O   | Inverting driver output pin, LVDS levels                                                                                                                                                      |
| 12  | D <sub>OUT3-</sub> |     |                                                                                                                                                                                               |
| 13  | D <sub>OUT2-</sub> |     |                                                                                                                                                                                               |
| 16  | D <sub>OUT1-</sub> |     |                                                                                                                                                                                               |
| 1   | EN                 | I   | Driver enable pin: When EN is low, the driver is disabled. When EN is high and EN* is low or open, the driver is enabled. If both EN and EN* are open circuit, then the driver is disabled.   |
| 8   | EN*                | I   | Driver enable pin: When EN* is high, the driver is disabled. When EN* is low or open and EN is high, the driver is enabled. If both EN and EN* are open circuit, then the driver is disabled. |
| 5   | GND                | —   | Ground pin                                                                                                                                                                                    |
| 4   | V <sub>CC</sub>    | —   | Power supply pin, +3.3 V ± 0.3 V                                                                                                                                                              |

## 6 Specifications

### 6.1 Absolute Maximum Ratings

See <sup>(1)</sup>

|                                                         |                                          |             | MIN        | MAX                   | UNIT  |
|---------------------------------------------------------|------------------------------------------|-------------|------------|-----------------------|-------|
| Supply voltage (V <sub>CC</sub> )                       |                                          |             | -0.3       | 4                     | V     |
| Input voltage (D <sub>IN</sub> )                        |                                          |             | -0.3       | V <sub>CC</sub> + 0.3 | V     |
| Enable input voltage (EN, EN*)                          |                                          |             | -0.3       | V <sub>CC</sub> + 0.3 | V     |
| Output voltage (D <sub>OUT+</sub> , D <sub>OUT-</sub> ) |                                          |             | -0.3       | 3.9                   | V     |
| Short-circuit duration                                  | (D <sub>OUT+</sub> , D <sub>OUT-</sub> ) |             | Continuous |                       |       |
| Maximum package power dissipation at +25°C              | PW0016A package                          |             | 866        |                       | mW    |
|                                                         | Derate PW0016A package                   | above +25°C | 6.9        |                       | mW/°C |
| Lead temperature                                        | Soldering (4 s)                          |             | 260        |                       | °C    |
| Maximum junction temperature                            |                                          |             | 150        |                       | °C    |
| Storage temperature, T <sub>stg</sub>                   |                                          |             | -65        | 150                   | °C    |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

|                                                    |                                                                                |  | VALUE | UNIT |
|----------------------------------------------------|--------------------------------------------------------------------------------|--|-------|------|
| $V_{(ESD)}$ Electrostatic discharge <sup>(1)</sup> | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(2)</sup>              |  | ±1200 | V    |
|                                                    | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(3)</sup> |  | ±200  |      |
|                                                    | Machine Model                                                                  |  | ±1200 |      |

- (1) ESD Ratings:  
HBM (1.5 kΩ, 100 pF)  
EIAJ (0 Ω, 200 pF)
- (2) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (3) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

|                                       | MIN | NOM | MAX | UNIT |
|---------------------------------------|-----|-----|-----|------|
| Supply voltage, $V_{CC}$              | 3   | 3.3 | 3.6 | V    |
| Operating free air temperature, $T_A$ | -40 | 25  | 85  | °C   |

### 6.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |                                              | DSLVD51047 | UNIT |
|-------------------------------|----------------------------------------------|------------|------|
|                               |                                              | PW (TSSOP) |      |
|                               |                                              | 16 PINS    |      |
| $R_{\theta JA}$               | Junction-to-ambient thermal resistance       | 114        | °C/W |
| $R_{\theta JC(top)}$          | Junction-to-case (top) thermal resistance    | 51         | °C/W |
| $R_{\theta JB}$               | Junction-to-board thermal resistance         | 59         | °C/W |
| $\psi_{JT}$                   | Junction-to-top characterization parameter   | 8          | °C/W |
| $\psi_{JB}$                   | Junction-to-board characterization parameter | 58         | °C/W |

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 6.5 Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified<sup>(1)(2)(3)</sup>

| PARAMETER                                                                                 | TEST CONDITIONS                                                                                                              | PIN                                    | MIN   | TYP  | MAX             | UNIT |
|-------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------|----------------------------------------|-------|------|-----------------|------|
| V <sub>OD1</sub> Differential output voltage                                              | R <sub>L</sub> = 100 Ω (Figure 18)                                                                                           | D <sub>OUT-</sub><br>D <sub>OUT+</sub> | 250   | 310  | 450             | mV   |
| ΔV <sub>OD1</sub> Change in magnitude of V <sub>OD1</sub> for complementary output states |                                                                                                                              |                                        |       | 1    | 35              | mV   |
| V <sub>OS</sub> Offset voltage                                                            |                                                                                                                              |                                        | 1.125 | 1.17 | 1.375           | V    |
| ΔV <sub>OS</sub> Change in magnitude of V <sub>OS</sub> for complementary output states   |                                                                                                                              |                                        |       | 1    | 25              | mV   |
| V <sub>OH</sub> Output high voltage                                                       |                                                                                                                              |                                        |       | 1.33 | 1.6             | V    |
| V <sub>OL</sub> Output low voltage                                                        |                                                                                                                              |                                        | 0.9   | 1.02 |                 | V    |
| V <sub>IH</sub> Input high voltage                                                        |                                                                                                                              | D <sub>IN</sub> ,<br>EN,<br>EN*        | 2     |      | V <sub>CC</sub> | V    |
| V <sub>IL</sub> Input low voltage                                                         |                                                                                                                              |                                        | GND   |      | 0.8             | V    |
| I <sub>IH</sub> Input high current                                                        | V <sub>IN</sub> = V <sub>CC</sub> or 2.5 V                                                                                   |                                        |       | 2    | 15              | μA   |
| I <sub>IL</sub> Input low current                                                         | V <sub>IN</sub> = GND or 0.4 V                                                                                               |                                        |       | 2    | 15              | μA   |
| V <sub>CL</sub> Input clamp voltage                                                       | I <sub>CL</sub> = -18 mA                                                                                                     |                                        | -1.5  | -0.8 |                 | V    |
| I <sub>OS</sub> Output short-circuit current <sup>(4)</sup>                               | ENABLED,<br>D <sub>IN</sub> = V <sub>CC</sub> , D <sub>OUT+</sub> = 0 V or<br>D <sub>IN</sub> = GND, D <sub>OUT-</sub> = 0 V | D <sub>OUT-</sub><br>D <sub>OUT+</sub> |       | -4   | -8              | mA   |
| I <sub>OSD</sub> Differential output short-circuit current <sup>(4)</sup>                 | ENABLED, V <sub>OD</sub> = 0 V                                                                                               |                                        |       | -4.2 | -9              | mA   |
| I <sub>OFF</sub> Power-off leakage                                                        | V <sub>OUT</sub> = 0 V or 3.6 V, V <sub>CC</sub> = 0 V or Open                                                               |                                        | -20   | ±1   | 20              | μA   |
| I <sub>OZ</sub> Output TRI-STATE current                                                  | EN = 0.8 V and EN* = 2.0 V<br>V <sub>OUT</sub> = 0 V or V <sub>CC</sub>                                                      |                                        | -10   | ±1   | 10              | μA   |
| I <sub>CC</sub> No load supply current drivers enabled                                    | D <sub>IN</sub> = V <sub>CC</sub> or GND                                                                                     | V <sub>CC</sub>                        |       | 4    | 8               | mA   |
| I <sub>CCL</sub> Loaded supply current drivers enabled                                    | R <sub>L</sub> = 100 Ω all channels, D <sub>IN</sub> = V <sub>CC</sub> or GND (all inputs)                                   |                                        |       | 20   | 30              | mA   |
| I <sub>CCZ</sub> No load supply current drivers disabled                                  | D <sub>IN</sub> = V <sub>CC</sub> or GND, EN = GND, EN* = V <sub>CC</sub>                                                    |                                        |       | 2.2  | 6               | mA   |

- (1) Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except: V<sub>OD1</sub> and ΔV<sub>OD1</sub>.
- (2) All typicals are given for: V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = +25°C.
- (3) The DSLVD1047 is a current mode device and only functions within datasheet specifications when a resistive load is applied to the driver outputs typical range is (90 Ω to 110 Ω).
- (4) Output short circuit current (I<sub>OS</sub>) is specified as magnitude only, minus sign indicates direction only.

## 6.6 Switching Characteristics

 $V_{CC} = +3.3V \pm 10\%$ ,  $T_A = -40^\circ C$  to  $+85^\circ C$  <sup>(1) (2) (3)</sup>

| PARAMETER  |                                                                | TEST CONDITIONS                                                   | MIN | TYP | MAX | UNIT |
|------------|----------------------------------------------------------------|-------------------------------------------------------------------|-----|-----|-----|------|
| $t_{PHLD}$ | Differential propagation delay high to low                     | $R_L = 100\ \Omega$ , $C_L = 15\ pF$<br>(Figure 19 and Figure 20) | 0.5 | 0.9 | 1.7 | ns   |
| $t_{PLHD}$ | Differential propagation delay low to high                     |                                                                   | 0.5 | 1.2 | 1.7 | ns   |
| $t_{SKD1}$ | Differential pulse skew $ t_{PHLD} - t_{PLHD} $ <sup>(4)</sup> |                                                                   |     | 0.3 | 0.4 | ns   |
| $t_{SKD2}$ | Channel-to-channel skew <sup>(5)</sup>                         |                                                                   |     | 0.4 | 0.5 | ns   |
| $t_{SKD3}$ | Differential part-to-part skew <sup>(6)</sup>                  |                                                                   | 0   |     | 1   | ns   |
| $t_{SKD4}$ | Differential part-to-part skew <sup>(7)</sup>                  |                                                                   | 0   |     | 1.2 | ns   |
| $t_{TLH}$  | Rise time                                                      |                                                                   |     | 0.5 | 1.5 | ns   |
| $t_{THL}$  | Fall time                                                      |                                                                   |     | 0.5 | 1.5 | ns   |
| $t_{PHZ}$  | Disable time high to Z                                         | $R_L = 100\ \Omega$ , $C_L = 15\ pF$<br>(Figure 21 and Figure 22) |     | 2   | 5   | ns   |
| $t_{PLZ}$  | Disable time low to Z                                          |                                                                   |     | 2   | 5   | ns   |
| $t_{PZH}$  | Enable time Z to high                                          |                                                                   |     | 3   | 7   | ns   |
| $t_{PZL}$  | Enable time Z to low                                           |                                                                   |     | 3   | 7   | ns   |
| $f_{MAX}$  | Maximum operating frequency <sup>(8)</sup>                     |                                                                   | 200 | 250 |     | MHz  |

(1) All typicals are given for:  $V_{CC} = 3.3\ V$ ,  $T_A = +25^\circ C$ .

(2) Generator waveform for all tests unless otherwise specified:  $f = 1\ MHz$ ,  $Z_O = 50\ \Omega$ ,  $t_r \leq 1\ ns$ , and  $t_f \leq 1\ ns$ .

(3)  $C_L$  includes probe and jig capacitance.

(4)  $t_{SKD1} |t_{PHLD} - t_{PLHD}|$  is the magnitude difference in differential propagation delay time between the positive going edge and the negative going edge of the same channel.

(5)  $t_{SKD2}$  is the differential channel-to-channel skew of any event on the same device.

(6)  $t_{SKD3}$ , differential part-to-part skew, is defined as the difference between the minimum and maximum specified differential propagation delays. This specification applies to devices at the same  $V_{CC}$  and within  $5^\circ C$  of each other within the operating temperature range.

(7)  $t_{SKD4}$ , part to part skew, is the differential channel-to-channel skew of any event between devices. This specification applies to devices over recommended operating temperature and voltage ranges, and across process distribution.  $t_{SKD4}$  is defined as  $|Max - Min|$  differential propagation delay.

(8)  $f_{MAX}$  generator input conditions:  $t_r = t_f < 1\ ns$  (0% to 100%), 50% duty cycle, 0 V to 3 V. Output criteria: duty cycle = 45% / 55%,  $V_{OD} > 250\ mV$ , all channels switching.

## 6.7 Typical Characteristics

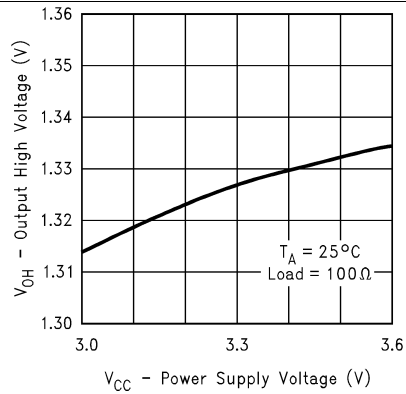


**Figure 2. Output High Voltage vs Power Supply Voltage**

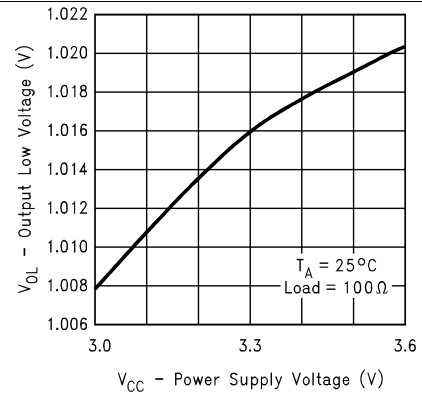


**Figure 3. Output Low Voltage vs Power Supply Voltage**

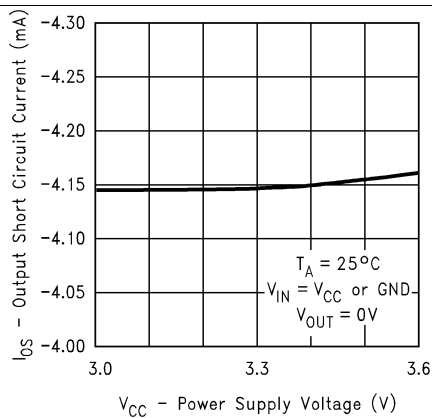


**Figure 4. Output Short Circuit Current vs Power Supply Voltage**

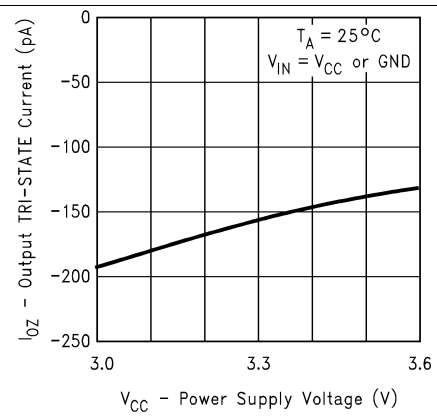


**Figure 5. Output TRI-STATE Current vs Power Supply Voltage**

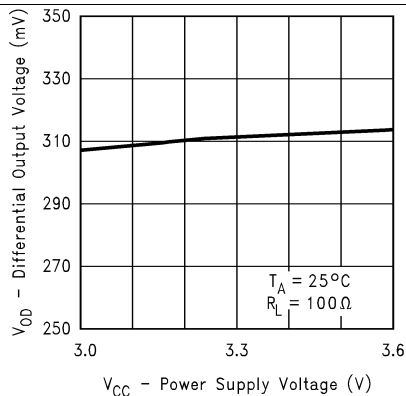


**Figure 6. Differential Output Voltage vs Power Supply Voltage**

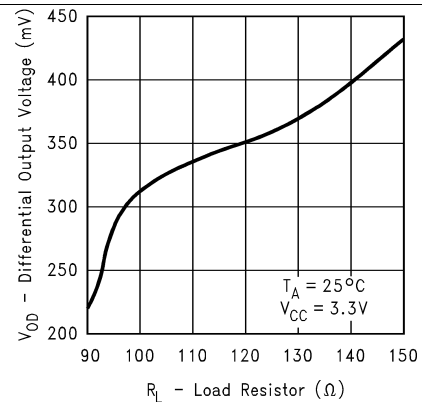
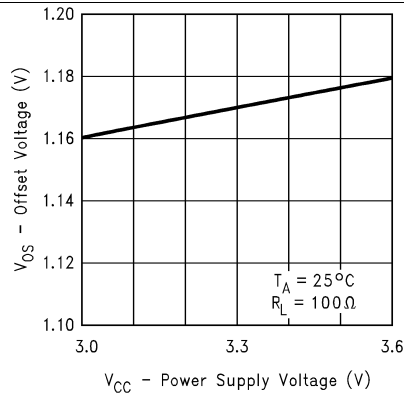
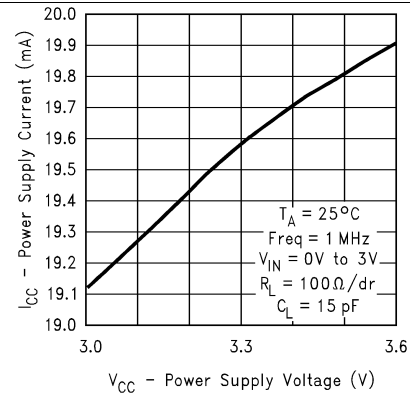
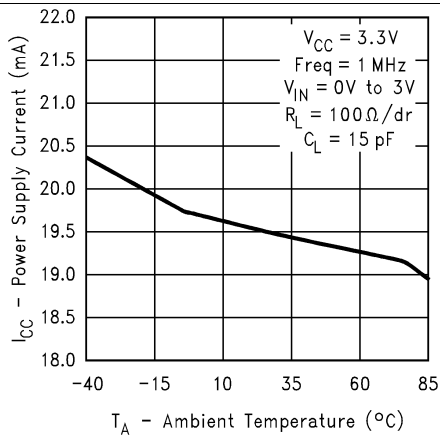
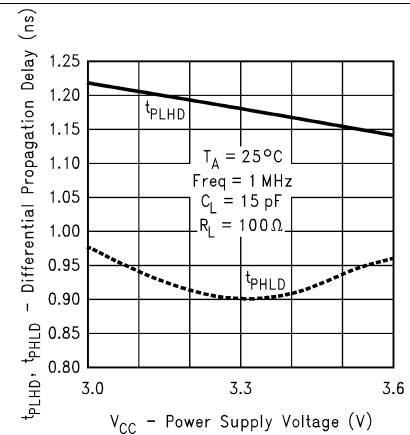
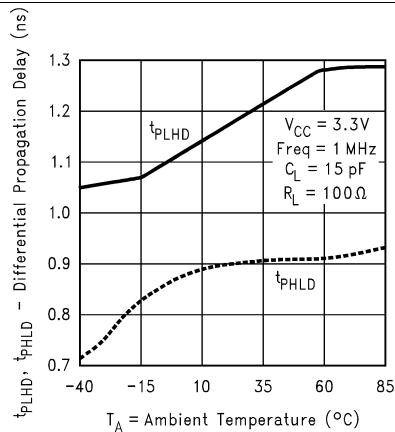
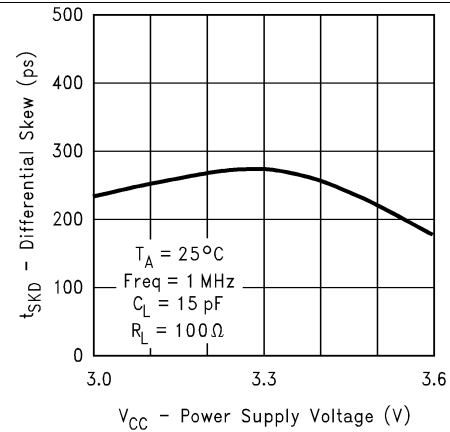


**Figure 7. Differential Output Voltage vs Load Resistor**

## Typical Characteristics (continued)


**Figure 8. Offset Voltage vs Power Supply Voltage**

**Figure 9. Power Supply Current vs Power Supply Voltage**

**Figure 10. Power Supply Current vs Ambient Temperature**

**Figure 11. Differential Propagation Delay vs Power Supply Voltage**

**Figure 12. Differential Propagation Delay vs Ambient Temperature**

**Figure 13. Differential Skew vs Power Supply Voltage**

## Typical Characteristics (continued)

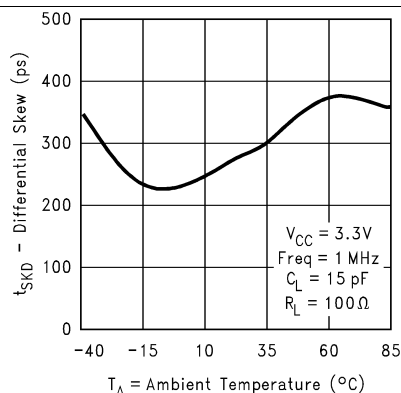


**Figure 14. Differential Skew vs Ambient Temperature**

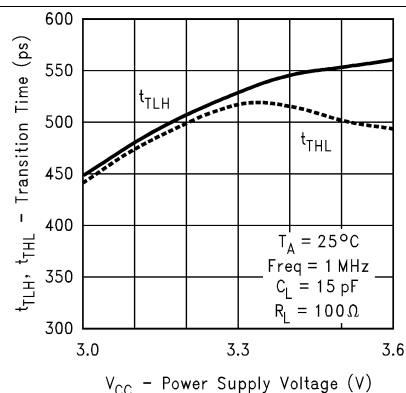


**Figure 15. Transition Time vs Power Supply Voltage**

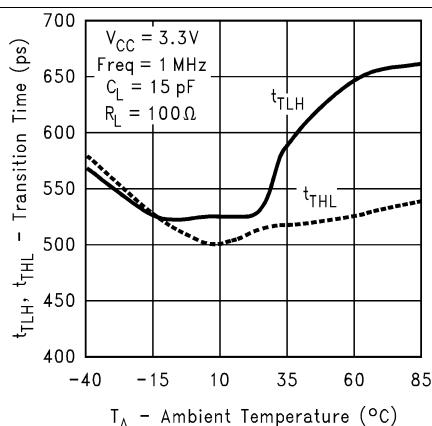


**Figure 16. Transition Time vs Ambient Temperature**

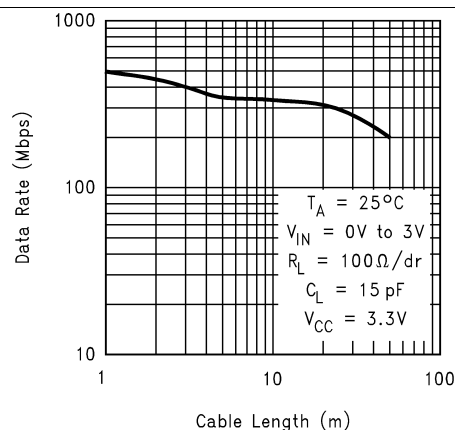


**Figure 17. Data Rate vs Cable Length**

## 7 Parameter Measurement Information

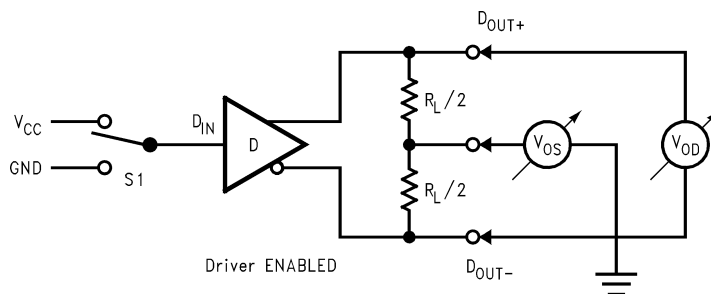


**Figure 18. Driver  $V_{OD}$  and  $V_{OS}$  Test Circuit**

## Parameter Measurement Information (continued)

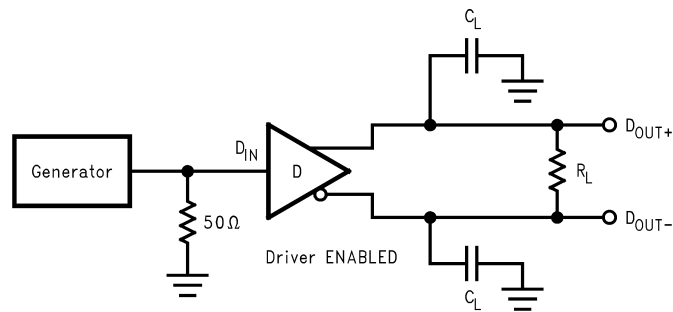


**Figure 19. Driver Propagation Delay and Transition Time Test Circuit**

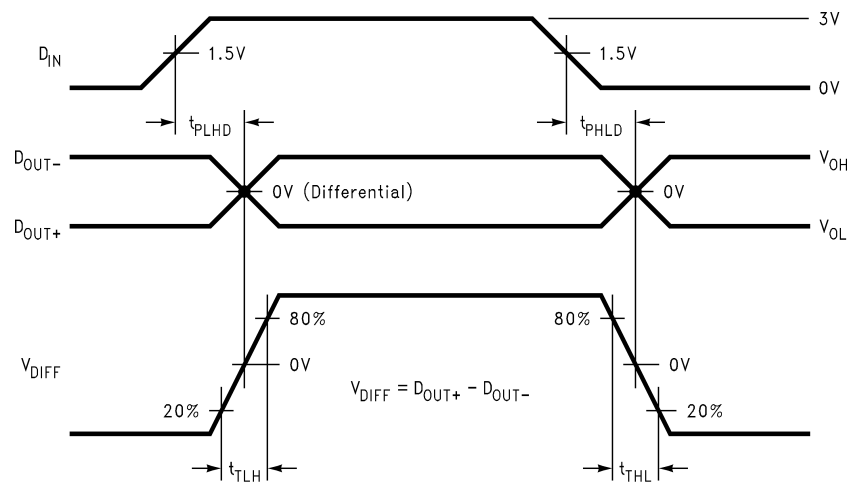


**Figure 20. Driver Propagation Delay and Transition Time Waveforms**

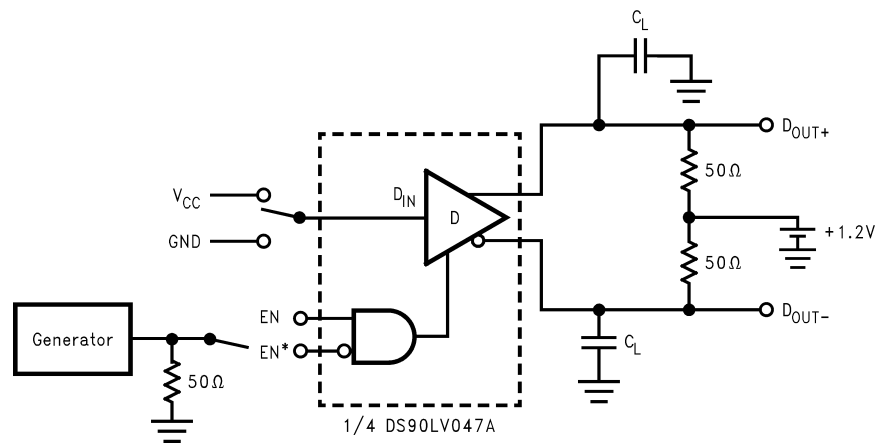


**Figure 21. Driver TRI-STATE Delay Test Circuit**

### Parameter Measurement Information (continued)

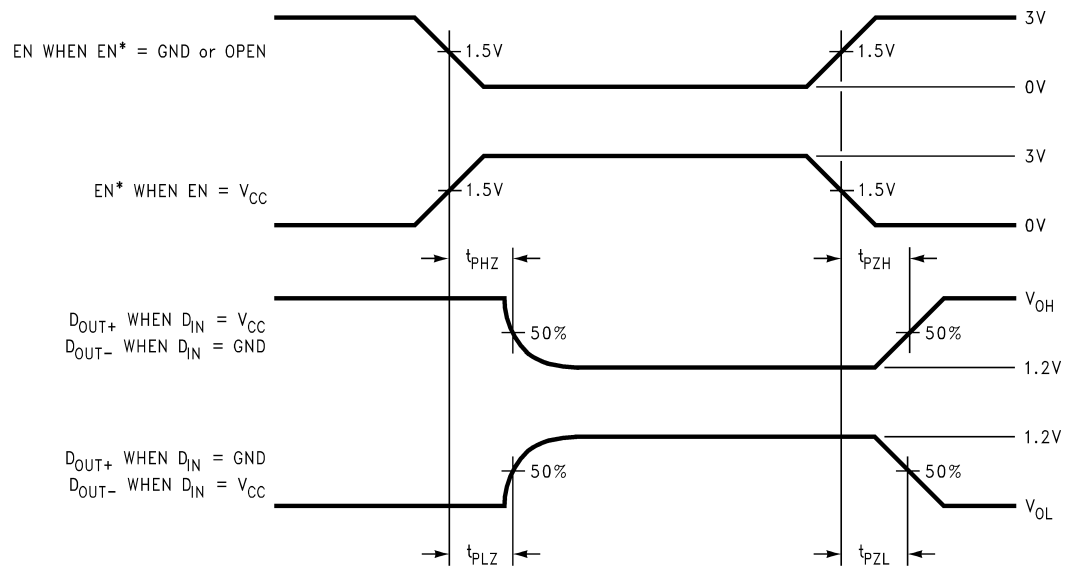


**Figure 22. Driver TRI-STATE Delay Waveform**

## 8 Detailed Description

### 8.1 Overview

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in [Figure 24](#). This configuration provides a clean signaling environment for the fast edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic differential impedance of the media is in the range of 100  $\Omega$ . A termination resistor of 100  $\Omega$  (selected to match the media), and is located as close to the receiver input pins as possible. The termination resistor converts the driver output current (current mode) into a voltage that is detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be taken into account.

The DSLVDSD1047 differential line driver is a balanced current source design. A current mode driver, generally speaking has a high output impedance and supplies a constant current for a range of loads (a voltage mode driver on the other hand supplies a constant voltage for a range of loads). Current is switched through the load in one direction to produce a logic state and in the other direction to produce the other logic state. The output current is typically 3.1 mA, a minimum of 2.5 mA, and a maximum of 4.5 mA. The current mode driver requires that a resistive termination be employed to terminate the signal and to complete the loop as shown in [Figure 24](#). AC or unterminated configurations are not allowed. The 3.1-mA loop current develops a differential voltage of 310 mV across the 100- $\Omega$  termination resistor which the receiver detects with a 250-mV minimum differential noise margin, (driven signal minus receiver threshold (250 mV – 100 mV = 150 mV). The signal is centered around +1.2 V (Driver Offset,  $V_{OS}$ ) with respect to ground as shown in [Figure 23](#).

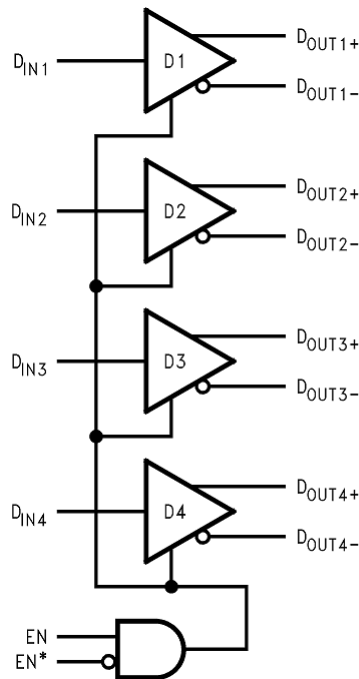
#### NOTE

The steady-state voltage ( $V_{SS}$ ) peak-to-peak swing is twice the differential voltage ( $V_{OD}$ ) and is typically 620 mV.

The current mode driver provides substantial benefits over voltage mode drivers, such as an RS-422 driver. Its quiescent current remains relatively flat versus switching frequency. Whereas the RS-422 voltage mode driver increases exponentially in most case from 20 MHz to 50 MHz. This is due to the overlap current that flows between the rails of the device when the internal gates switch. Whereas the current mode driver switches a fixed current between its output without any substantial overlap current. This is similar to some ECL and PECL devices, but without the heavy static  $I_{CC}$  requirements of the ECL/PECL designs. LVDS requires > 80% less current than similar PECL devices. AC specifications for the driver are a tenfold improvement over other existing RS-422 drivers.

The TRI-STATE function allows the driver outputs to be disabled, thus obtaining an even lower power state when the transmission of data is not required.

## 8.2 Functional Block Diagram



## 8.3 Feature Description

### 8.3.1 LVDS Fail-Safe

This section addresses the common concern of fail-safe biasing of LVDS interconnects, specifically looking at the DSLVD1047 driver outputs and the DSLVD1048 receiver inputs.

The LVDS receiver is a high-gain, high-speed device that amplifies a small differential signal (20 mV) to CMOS logic levels. Due to the high gain and tight threshold of the receiver, take care to prevent noise from appearing as a valid signal.

The internal fail-safe circuitry of the receiver is designed to source or sink a small amount of current, providing fail-safe protection (a stable known state of HIGH output voltage) for floating, terminated, or shorted receiver inputs.

1. **Open Input Pins.** The DSLVD1048 is a quad receiver device, and if an application requires only 1, 2, or 3 receivers, the unused channel(s) inputs must be left OPEN. Do not tie unused receiver inputs to ground or any other voltages. The input is biased by internal high value pullup and pulldown resistors to set the output to a HIGH state. This internal circuitry ensures a HIGH, stable output state for open inputs.
2. **Terminated Input.** If the DSLVD1047 driver is disconnected (cable unplugged), or if the DSLVD1047 driver is in a TRI-STATE or power-off condition, the receiver output is again in a HIGH state, even with the end of cable 100-Ω termination resistor across the input pins. The unplugged cable can become a floating antenna which can pick up noise. If the cable picks up more than 10 mV of differential noise, the receiver may see the noise as a valid signal and switch. To insure that any noise is seen as common-mode and not differential, a balanced interconnect must be used. Twisted pair cable offers better balance than flat ribbon cable.
3. **Shorted Inputs.** If a fault condition occurs that shorts the receiver inputs together, thus resulting in a 0-V differential input voltage, the receiver output remains in a HIGH state. Shorted input fail-safe is not supported across the common-mode range of the device (GND to 2.4 V). It is only supported with inputs shorted and no external common-mode voltage applied.

## Feature Description (continued)

External lower value pullup and pulldown resistors (for a stronger bias) may be used to boost fail-safe in the presence of higher noise levels. The pullup and pulldown resistors should be in the 5-k $\Omega$  to 15-k $\Omega$  range to minimize loading and waveform distortion to the driver. The common-mode bias point should be set to approximately 1.2 V (less than 1.75 V) to be compatible with the internal circuitry.

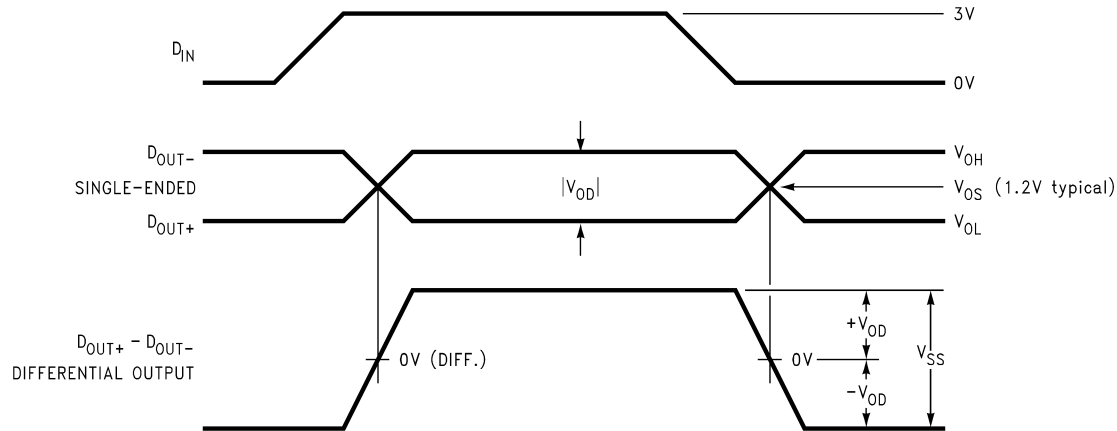


**Figure 23. Driver Output Levels**

## 8.4 Device Functional Modes

Table 1 lists the functional modes DSLVD1047.

**Table 1. Truth Table**

| ENABLES                                 |           | INPUT           | OUTPUTS           |                   |
|-----------------------------------------|-----------|-----------------|-------------------|-------------------|
| EN                                      | EN*       | D <sub>IN</sub> | D <sub>OUT+</sub> | D <sub>OUT-</sub> |
| H                                       | L or Open | L               | L                 | H                 |
|                                         |           | H               | H                 | L                 |
| All other combinations of ENABLE inputs |           | X               | Z                 | Z                 |

## 9 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The DSLVD1047 has a flow-through pinout that allows for easy PCB layout. The LVDS signals on one side of the device easily allows for matching electrical lengths of the differential pair trace lines between the driver and the receiver as well as allowing the trace lines to be close together to couple noise as common-mode. Noise isolation is achieved with the LVDS signals on one side of the device and the TTL signals on the other side.

### 9.2 Typical Application

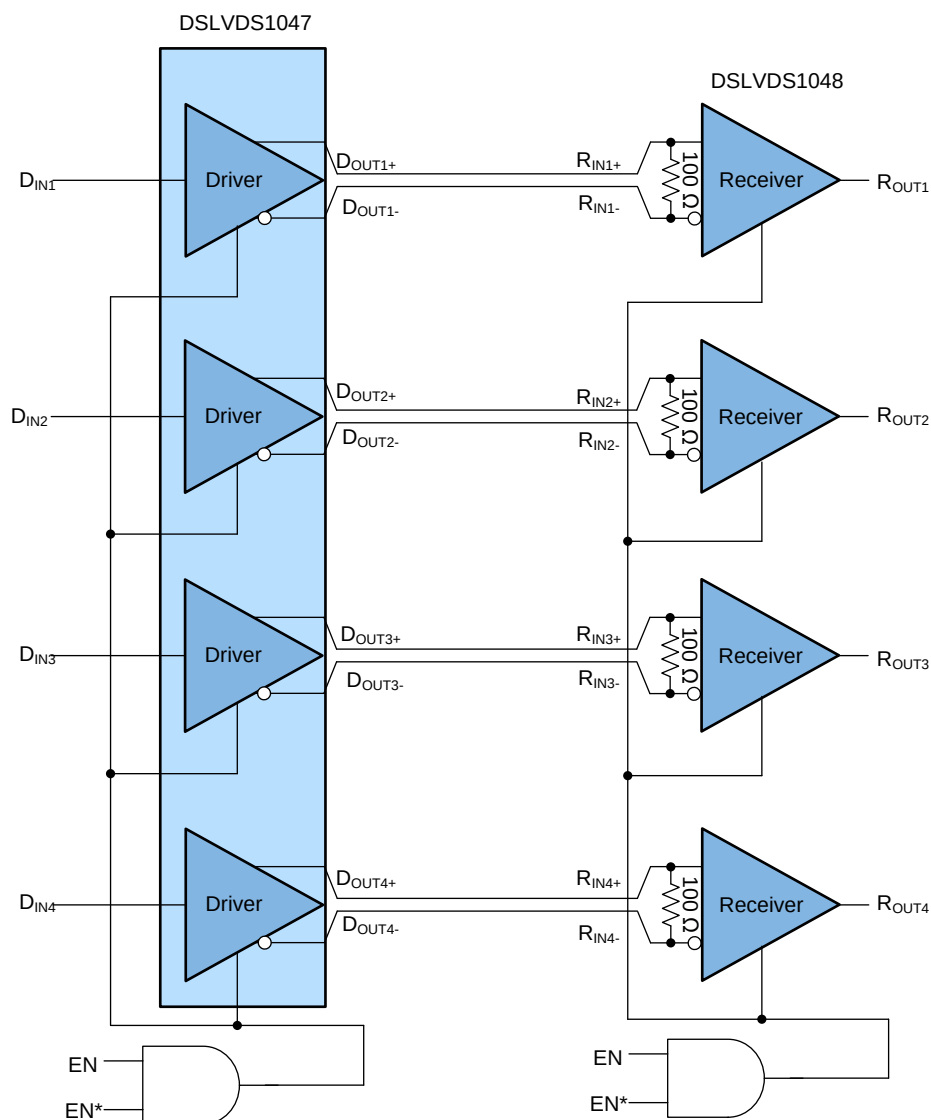


Figure 24. Point-to-Point Application

## Typical Application (continued)

### 9.2.1 Design Requirements

When using LVDS devices, it is important to remember to specify controlled impedance PCB traces, cable assemblies, and connectors. All components of the transmission media should have a matched differential impedance of about 100  $\Omega$ . They should not introduce major impedance discontinuities.

Balanced cables (for example, twisted pair) are usually better than unbalanced cables (ribbon cable) for noise reduction and signal quality. Balanced cables tend to generate less EMI due to field canceling effects and also tend to pick up electromagnetic radiation as common-mode (not differential mode) noise which is rejected by the LVDS receiver.

For cable distances  $< 0.5$  M, most cables can be made to work effectively. For distances  $0.5 \text{ M} \leq d \leq 10 \text{ M}$ , CAT5 (Category 5) twisted pair cable works well, is readily available and relatively inexpensive.

**Table 2. Design Requirements**

| DESIGN PARAMETERS                        | EXAMPLE VALUE  |
|------------------------------------------|----------------|
| Driver Supply Voltage ( $V_{CC}$ )       | 3.0 to 3.6 V   |
| Driver Input Voltage                     | 0 to 3.6 V     |
| Driver Signaling Rate                    | DC to 400 Mbps |
| Interconnect Characteristic Impedance    | 100 $\Omega$   |
| Termination Resistance                   | 100 $\Omega$   |
| Number of Receiver Nodes                 | 1              |
| Ground shift between driver and receiver | $\pm 1$ V      |

### 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Probing LVDS Transmission Lines

Always use high impedance ( $> 100 \text{ k}\Omega$ ), low capacitance ( $< 2 \text{ pF}$ ) scope probes with a wide bandwidth (1 GHz) scope. Improper probing gives deceiving results.

#### 9.2.2.2 Data Rate vs Cable Length Graph Test Procedure

A pseudo-random bit sequence (PRBS) of  $2^9-1$  bits was programmed into a function generator (Tektronix HFS9009) and connected to the driver inputs through 50- $\Omega$  cables and SMB connectors. An oscilloscope (Tektronix 11801B) was used to probe the resulting eye pattern, measured differentially at the input to the receiver. A 100- $\Omega$  resistor was used to terminate the pair at the far end of the cable. The measurements were taken at the far end of the cable, at the input of the receiver, and used for the jitter analysis for this graph (Figure 17). The frequency of the input signal was increased until the measured jitter ( $t_{jcs}$ ) equaled 20% with respect to the unit interval ( $t_{ui}$ ) for the particular cable length under test. Twenty percent jitter is a reasonable place to start with many system designs. The data used was NRZ. Jitter was measured at the 0-V differential voltage of the differential eye pattern. The DSLVDS1047 and DSLVDS1048 can be evaluated using the new DS90LV047-048AEVM.

Figure 25 shows very good typical performance that can be used as a design guideline for data rate vs cable length. Increasing the jitter percentage increases the curve respectively, allowing the device to transmit faster over longer cable lengths. This relaxes the jitter tolerance of the system allowing more jitter into the system, which could reduce the reliability and efficiency of the system. Alternatively, decreasing the jitter percentage has the opposite effect on the system. The area under the curve is considered the safe operating area based on the above signal quality criteria. For more information on eye pattern testing, please see [AN-808 Long Transmission Lines and Data Signal Quality](#) (SNLA028).

### 9.2.3 Application Curve

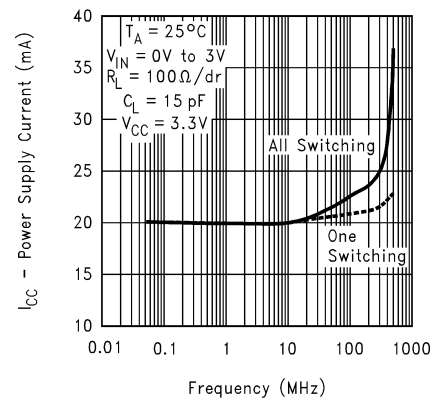


**Figure 25. Power Supply Current vs Frequency**

## 10 Power Supply Recommendations

Although the DSLVDS1047 draws very little power while at rest. At higher switching frequencies there is a dynamic current component which increases the overall power consumption. The DSLVDS1047 power supply connection must take this additional current consumption into consideration for maximum power requirements.

## 11 Layout

### 11.1 Layout Guidelines

- Use at least 4 PCB layers (top to bottom); LVDS signals, ground, power, TTL signals.
- Isolate TTL signals from LVDS signals, otherwise the TTL may couple onto the LVDS lines. It is best to put TTL and LVDS signals on different layers which are isolated by a power/ground plane(s).
- Keep drivers and receivers as close to the (LVDS port side) connectors as possible.

#### 11.1.1 Power Decoupling Recommendations

Bypass capacitors must be used on power pins. Use high frequency ceramic (surface mount is recommended) 0.1- $\mu$ F and 0.001- $\mu$ F capacitors in parallel at the power supply pin with the smallest value capacitor closest to the device supply pin. Additional scattered capacitors over the printed-circuit board improves decoupling. Multiple vias must be used to connect the decoupling capacitors to the power planes. A 10- $\mu$ F (35-V) or greater solid tantalum capacitor must be connected at the power entry point on the printed-circuit board between the supply and ground.

#### 11.1.2 Differential Traces

Use controlled impedance traces which match the differential impedance of your transmission medium (that is, cable) and termination resistor. Run the differential pair trace lines as close together as possible as soon as they leave the IC (stubs must be < 10 mm long). This helps eliminate reflections and ensure noise is coupled as common-mode. In fact, we have seen that differential signals which are 1 mm apart radiate far less noise than traces 3 mm apart since magnetic field cancellation is much better with the closer traces. In addition, noise induced on the differential lines is much more likely to appear as common-mode which is rejected by the receiver.

Match electrical lengths between traces to reduce skew. Skew between the signals of a pair means a phase difference between signals, which destroys the magnetic field cancellation benefits of differential signals and EMI, results.

---

#### NOTE

The velocity of propagation,  $v = c/\epsilon_r$  where  $c$  (the speed of light) = 0.2997mm/ps or 0.0118 in/ps

---

Do not rely solely on the autoroute function for differential traces. Carefully review dimensions to match differential impedance and provide isolation for the differential lines. Minimize the number of vias and other discontinuities on the line.

Avoid 90° turns (these cause impedance discontinuities). Use arcs or 45° bevels.

Within a pair of traces, the distance between the two traces must be minimized to maintain common-mode rejection of the receivers. On the printed-circuit board, this distance must remain constant to avoid discontinuities in differential impedance. Minor violations at connection points are allowable.

#### 11.1.3 Termination

Use a termination resistor which best matches the differential impedance of your transmission line. The resistor must be between 90  $\Omega$  and 130  $\Omega$ . Remember that the current mode outputs need the termination resistor to generate the differential voltage. LVDS does not work without resistor termination. Typically, connecting a single resistor across the pair at the receiver end will suffice.

## Layout Guidelines (continued)

Surface mount 1% to 2% resistors are best. PCB stubs, component lead, and the distance from the termination to the receiver inputs must be minimized. The distance between the termination resistor and the receiver should be < 10 mm (12 mm maximum).

### 11.2 Layout Example

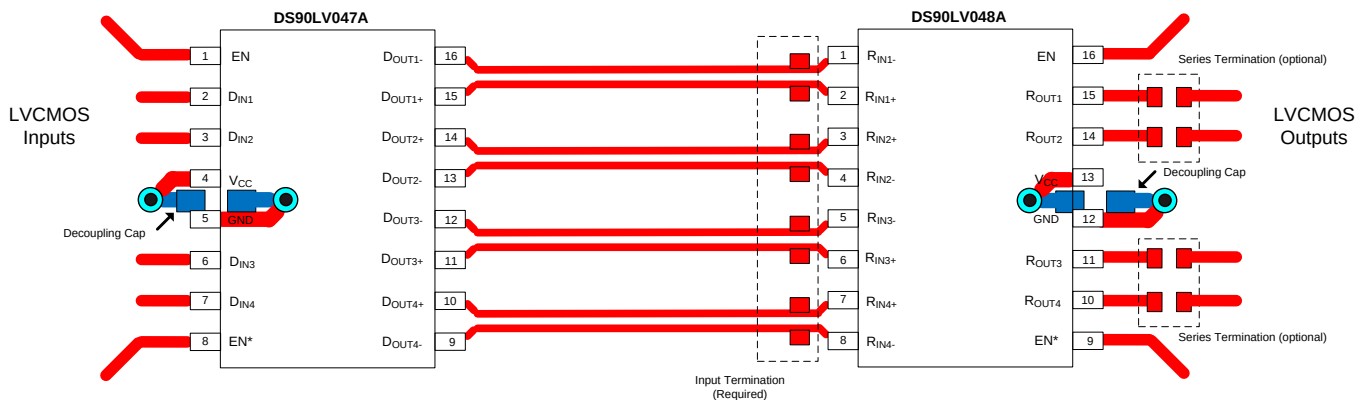


**Figure 26. Layout Recommendation**

## 12 Device and Documentation Support

### 12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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### 12.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

| Orderable part number         | Status<br>(1) | Material type<br>(2) | Package   Pins  | Package qty   Carrier | RoHS<br>(3) | Lead finish/<br>Ball material<br>(4) | MSL rating/<br>Peak reflow<br>(5) | Op temp (°C) | Part marking<br>(6) |
|-------------------------------|---------------|----------------------|-----------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| <a href="#">DSLVDS1047PWR</a> | Active        | Production           | TSSOP (PW)   16 | 2500   LARGE T&R      | Yes         | SN                                   | Level-1-260C-UNLIM                | -40 to 85    | DSLVDS<br>1047      |
| DSLVDS1047PWR.B               | Active        | Production           | TSSOP (PW)   16 | 2500   LARGE T&R      | Yes         | SN                                   | Level-1-260C-UNLIM                | -40 to 85    | DSLVDS<br>1047      |
| <a href="#">DSLVDS1047PWT</a> | Active        | Production           | TSSOP (PW)   16 | 250   SMALL T&R       | Yes         | SN                                   | Level-1-260C-UNLIM                | -40 to 85    | DSLVDS<br>1047      |
| DSLVDS1047PWT.B               | Active        | Production           | TSSOP (PW)   16 | 250   SMALL T&R       | Yes         | SN                                   | Level-1-260C-UNLIM                | -40 to 85    | DSLVDS<br>1047      |

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

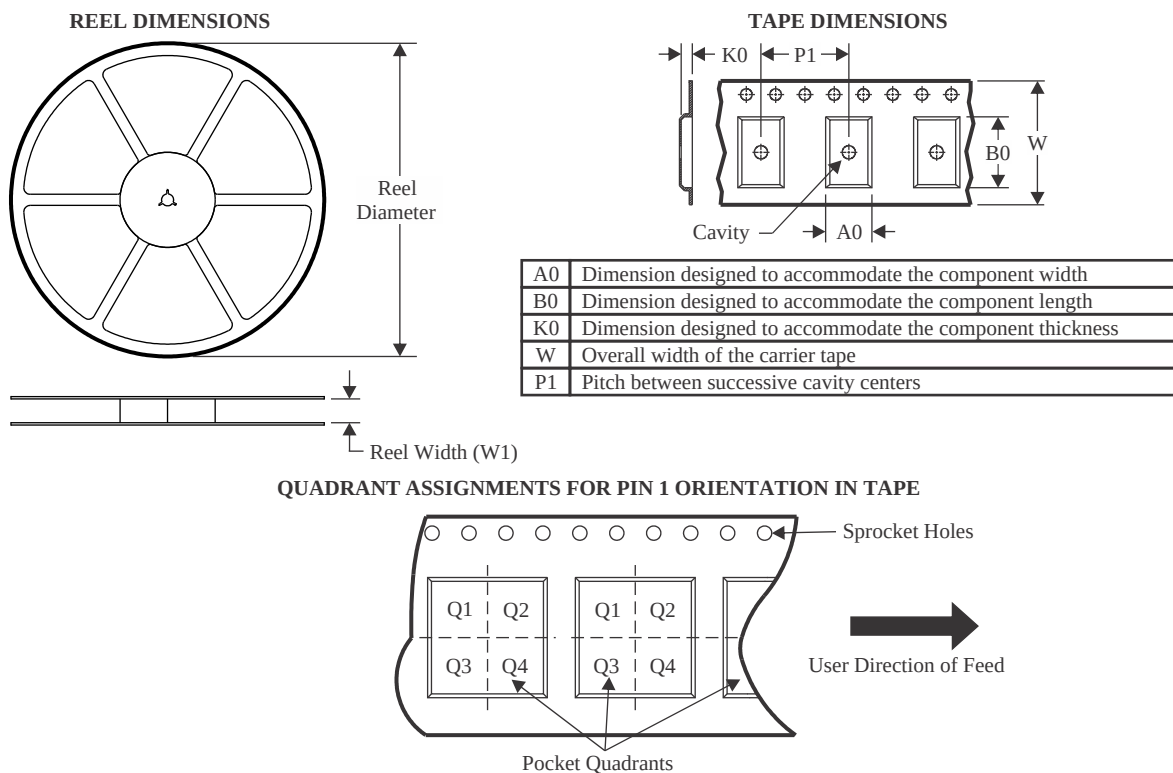
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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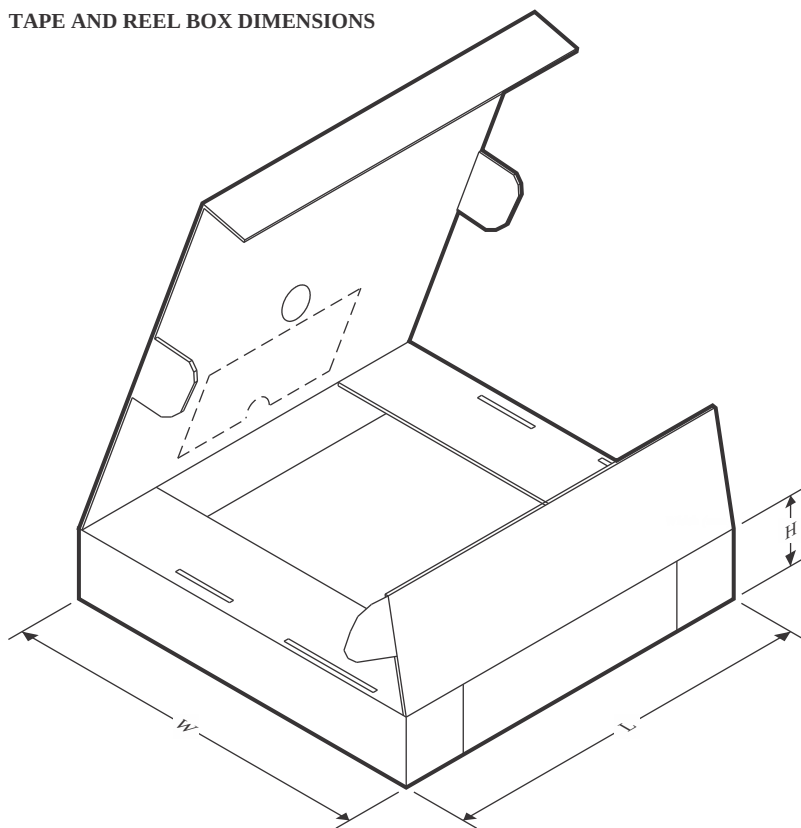
## TAPE AND REEL INFORMATION



\*All dimensions are nominal

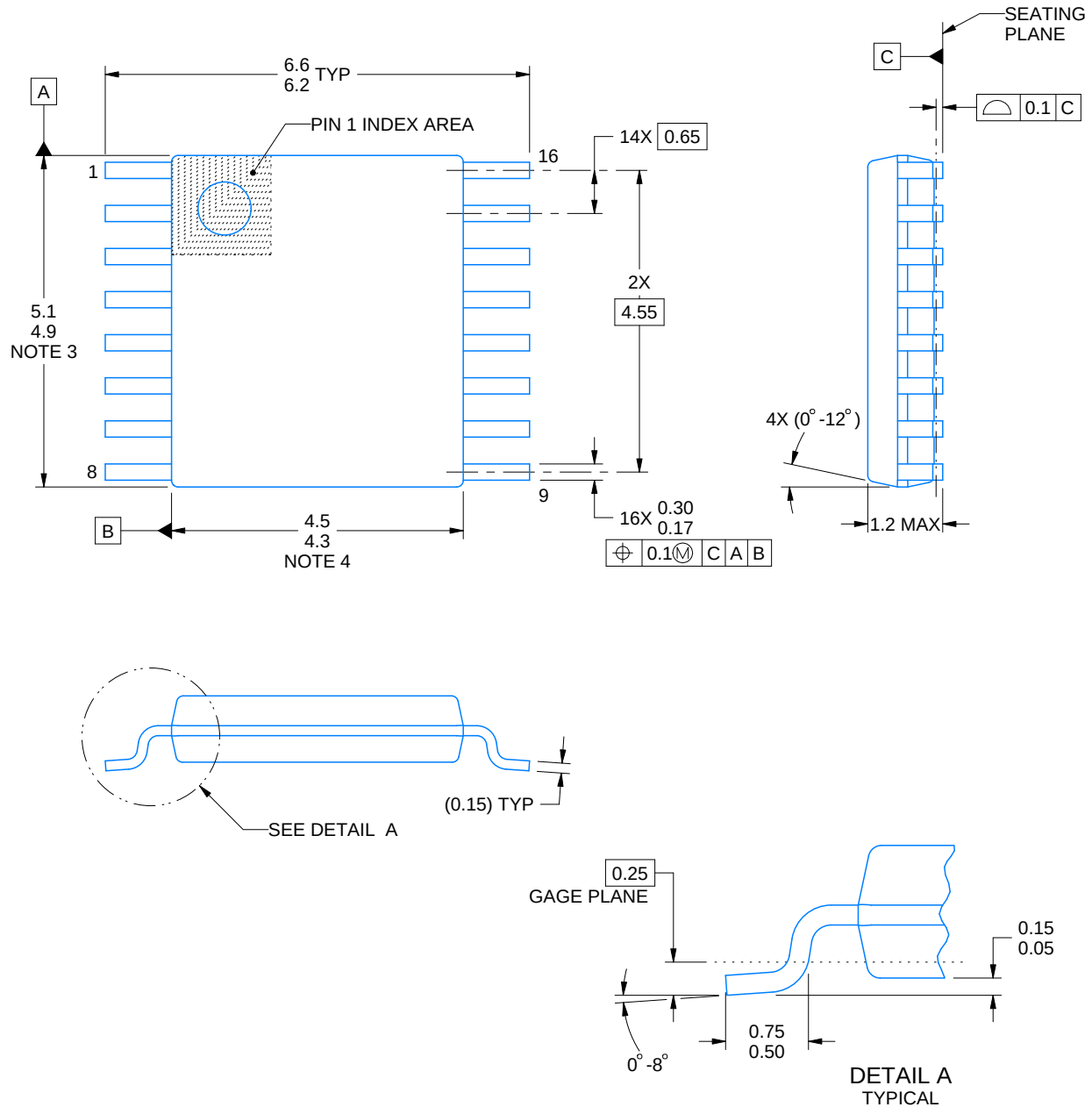
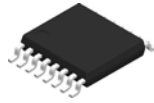
| Device       | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|--------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| DSLVD1047PWR | TSSOP        | PW              | 16   | 2500 | 330.0              | 12.4               | 6.95    | 5.6     | 1.6     | 8.0     | 12.0   | Q1            |
| DSLVD1047PWT | TSSOP        | PW              | 16   | 250  | 177.8              | 12.4               | 6.95    | 5.6     | 1.6     | 8.0     | 12.0   | Q1            |

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

| Device       | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|--------------|--------------|-----------------|------|------|-------------|------------|-------------|
| DSLVD1047PWR | TSSOP        | PW              | 16   | 2500 | 367.0       | 367.0      | 35.0        |
| DSLVD1047PWT | TSSOP        | PW              | 16   | 250  | 210.0       | 185.0      | 35.0        |



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## NOTES:

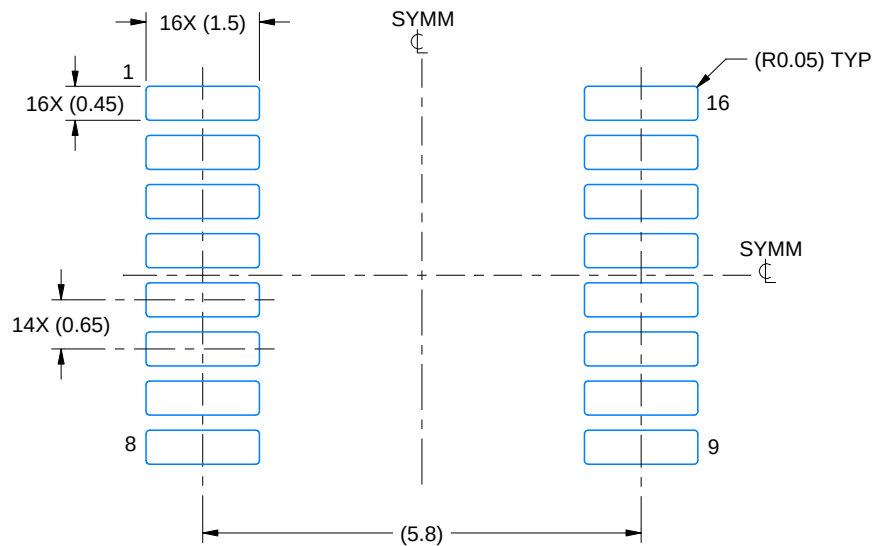
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-153.

# EXAMPLE BOARD LAYOUT

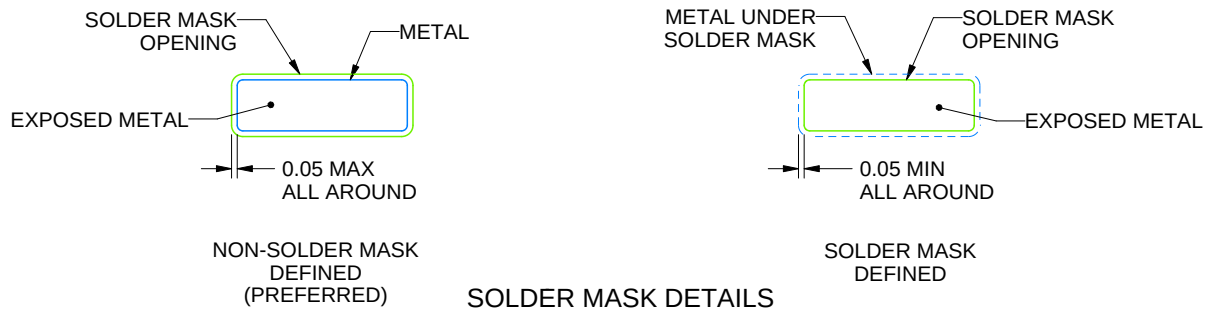
PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 10X



4220204/B 12/2023

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

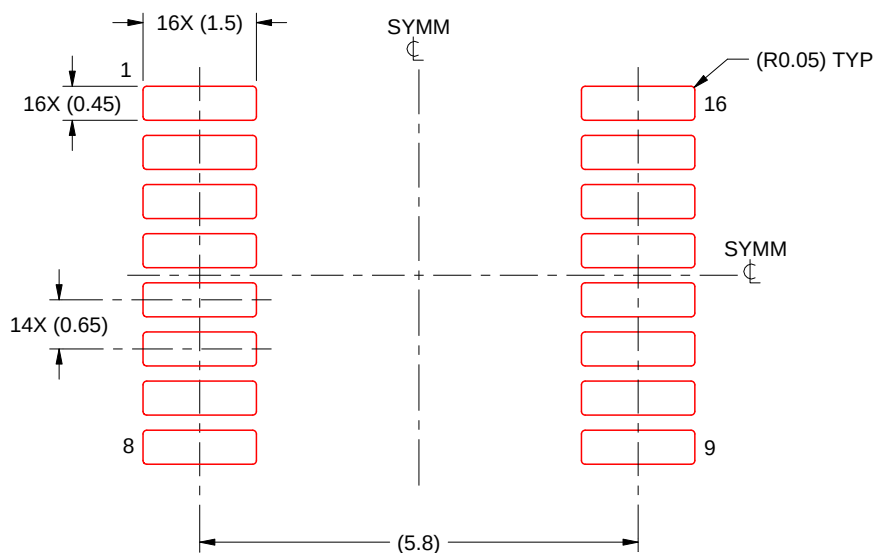
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE: 10X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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